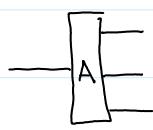


Example 2

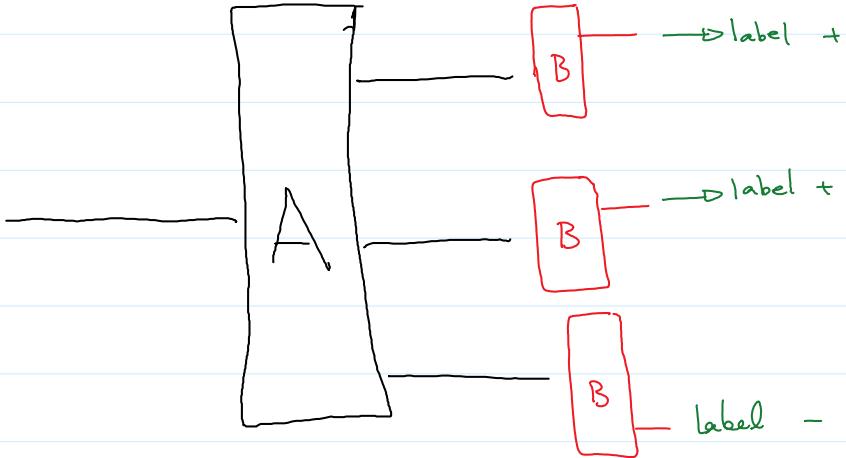
Consider the following setting



$$\{ |1\rangle, |2\rangle, |3\rangle \}$$

$$|\psi\rangle = \alpha|1\rangle + \beta|2\rangle + \gamma|3\rangle$$

Also



Take input state to be  $|\psi\rangle = \frac{1}{\sqrt{3}}[|1\rangle + |2\rangle + |3\rangle]$

What happens if  $\underline{B}$  is measured?

Probabilities

$$+ \quad \Pr(+)=|\langle\psi|_0\rangle|^2 + |\langle\psi|_1\rangle|^2 = \langle\psi|\pi_+|\psi\rangle + \langle\psi|\pi_1|\psi\rangle \\ = \langle\psi|\pi_+|\psi\rangle = \frac{2}{3}$$

$$\pi_+ = \pi_0 + \pi_1$$

$$- \quad \Pr(-) = |\langle\psi|2\rangle|^2 = \frac{1}{3}$$

States

$$- \Rightarrow \frac{\pi_- |\psi\rangle}{\sqrt{\Pr(-)}} = |2\rangle$$

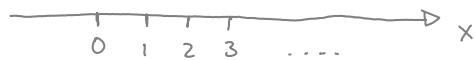
$$+ \Rightarrow \pi_+ |\psi\rangle - |0\rangle + |1\rangle \rightarrow \text{Need to}$$

$\psi^{1s}(-)$

$$+ \Rightarrow \frac{|\psi_+| + |\psi_-|}{\sqrt{\Pr(+)}} = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$$

→ Need to check something.

### Example 3



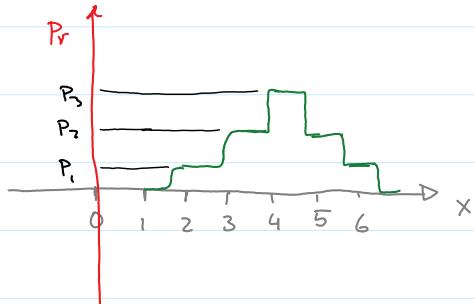
What's the corresponding Hilbert space?

What's the basis?

$\mathcal{H} = \text{Span} \{ |x_1\rangle, |x_2\rangle, \dots \}$  → Infinite dimensional Hilbert space.

$$\Pi_x = I \times X \times I$$

→ Some initial state



$$|\psi_{in}\rangle = \sqrt{P_1} |x_1\rangle + \sqrt{P_2} |x_2\rangle + \sqrt{P_3} |x_3\rangle + \sqrt{P_4} |x_4\rangle + \sqrt{P_5} |x_5\rangle + \sqrt{P_6} |x_6\rangle$$

$$\Pr(x_3) = \langle \psi_{in} | \Pi_{x_3} | \psi_{in} \rangle = \sqrt{P_2} \sqrt{P_2}^* = P_2$$

A Is  $|\psi_{in}\rangle$  unique? or

Is this the only  $|\psi_{in}\rangle$  that can give the probability distribution above?

If not, what freedoms are there?

Make one more  $|\psi_{in}\rangle$  that is compatible with the

Probability distribution.

What's the prob. of getting  $x \in \{x_1, x_3\}$  ?

$$\Pi_{2,3} = |x_2 \times x_1| + |x_3 \times x_3|$$

$$Pr = \langle \psi | \Pi_{2,3} | \psi \rangle$$

Also note that  $\sum_i Pr(x_i) = 1$

What if  $\Delta x \neq 1$ ?

\* Continuous limit

$$x \in \mathbb{R}$$



$$\mathcal{H} = \text{span} \{ |x\rangle : x \in \mathbb{R} \}$$

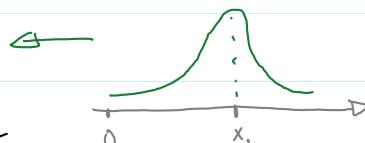
Well come back  
to this, there's a

$$\Pi_x = |x \times x|$$

problem with these states.

What's the analogue of the initial state above?

Gaussian distribution



$$|\psi_{in}\rangle = \int_{-\infty}^{\infty} dx \sqrt{\frac{-}{2\sigma^2}} e^{-\frac{(x-x_0)^2}{2\sigma^2}} |x\rangle$$

- Check that this gives the right probability distribution

- Again, the state compatible with the " " is not unique.

What's the prob. distribution?

$$|\psi(t)\rangle = \int dx |x\rangle \langle x| \psi(t)\rangle = \int \psi(x,t) |x\rangle dx$$

Normalization:  $\langle \psi(t) | \psi(t) \rangle = \int dx \int dx' \psi(x,t) \psi^*(x',t) \langle x' | x \rangle$

$\langle x | x' \rangle = \delta(x-x') \rightarrow$  Orthonormality of the basis elements.

$$= \int dx |\psi(x,t)|^2 = 1 \rightarrow$$
 Square-integrable functions. (SI)

$|x'\rangle \rightarrow$  Are the basis elements SI?

$$|x'\rangle = \int dx \underbrace{\langle x | x' \rangle}_{\psi(x)} |x\rangle$$

$$\psi(x) = \delta(x-x')$$

$$\int dx |\delta(x-x')|^2 ? \rightarrow \text{Not SI}.$$

Probability vs Probability density

What's the prob. of getting some outcome between  $x_1$  &  $x_2$ ?



$$\Pi_{x_1 \dots x_2} = \int_{x_1}^{x_2} |x\rangle \langle x| dx$$

$$\Pr([x_1, x_2]) = \dots = \int_{x_1}^{x_2} |\psi(x, t)|^2 dx$$

Normalization

$\int_{-\infty}^{\infty} dx |\psi(x, t)|^2 = 1 \rightarrow$  So  $|\psi(x, t)|^2$  cannot be probability. It has units of  $\frac{1}{x}$ .

$\Pr(x_i) \rightarrow$  This is problematic.  $\rightarrow$  Why?

$$x \in [x, x+dx]$$

$\Pr([x, x+dx]) = |\psi(x, t)|^2 dx \rightarrow$  Check with the discrete limit.

$|\psi(x, t)|^2 \rightarrow$  Probability density.

Change of basis

$\langle \hat{p} \rangle = \langle \psi | \hat{p} | \psi \rangle \rightarrow$  What's the momentum?

$$|\psi(t)\rangle = \int \underbrace{p \times p |\psi(t)\rangle}_{\tilde{\psi}(p, t)} dp$$

$$|\psi\rangle = \sum c_i |i\rangle \rightarrow \hat{p} = \sum \tilde{c}_i |\tilde{i}\rangle$$

$$c_i \xrightarrow{?} \tilde{c}_i$$

$$\tilde{\psi}(p,t) \rightarrow \psi(x,t)$$

$$\psi(x,t) = \langle x | \psi(t) \rangle = \langle x | \hat{u} | \psi(t) \rangle =$$

$$\int dp \langle x | p \rangle \langle p | \psi(t) \rangle = \int dp \langle x | p \rangle \underbrace{\tilde{\psi}(p,t)}_{\downarrow} \\ \underline{\text{We need this.}}$$

$$\hat{X} \longleftrightarrow \hat{P}$$

$$\{x, p\} = 1 \Rightarrow [x, p] = i\hbar \mathbb{1}$$

$$\underbrace{\langle x | p \rangle}_{?}$$

(A)

Prove that

$$e^{iA\lambda} B e^{-iA\lambda} = B + i[A, B] + \frac{i^2}{2!} [A, [A, B]] + \dots$$

(B)

Prove that

$$e^{i\hat{p}_x \lambda} x e^{-i\hat{p}_x \lambda} = \hat{x} + a \mathbb{1}$$

How does this equality help?

Consider this state:

$$|\psi\rangle = e^{-i\frac{\alpha}{\hbar}\hat{p}} |x\rangle$$

$$|\psi\rangle = e^{-\frac{p}{\hbar}} |x\rangle$$

$$\hat{x}|\psi\rangle = x \hat{e}^{-\frac{i\alpha}{\hbar}\hat{p}} |\psi\rangle = e^{-\frac{i\alpha}{\hbar}\hat{p}} (\hat{x} + \alpha \hat{1}) |\psi\rangle \\ = e^{-\frac{i\alpha}{\hbar}\hat{p}} (x + \alpha) |\psi\rangle = (x + \alpha) \underbrace{e^{-\frac{i\alpha}{\hbar}\hat{p}}}_{|\phi\rangle} |\psi\rangle$$

So,  $|\phi\rangle$  is an eigenstate of  $\hat{x}$  with eigenvalue  $x + \alpha$

$$\Rightarrow |\phi\rangle = |x + \alpha\rangle$$

(A) Is this always true (for any operator)?

Now let's calculate

$$\langle p | e^{-\frac{i\alpha}{\hbar}\hat{p}} | x \rangle = e^{-\frac{i\alpha p}{\hbar}} \langle p | x \rangle \\ = \langle p | x + \alpha \rangle$$

Let's take  $\langle p | x \rangle = f(x, p)$ . The equality above states that

$$e^{-\frac{i\alpha p}{\hbar}} f(x, p) = f(x + \alpha, p)$$

This indicates

$$f(x, p) = A e^{-\frac{i x \cdot p}{\hbar}}$$

To see this take  $\alpha \rightarrow \delta x \ll 1$

$$\underline{\text{LHS}} : f(x, p) + \frac{df}{dx} \delta x$$

$$\underline{\text{RHS}} : f(x, p) - i \frac{p}{\hbar} \delta x \\ \Rightarrow \frac{df}{dx} = -i \frac{p}{\hbar} \Rightarrow f(x, p) = A e^{-\frac{ipx}{\hbar}}$$

$S_0$

$$-\frac{ip}{\hbar} x p$$

$$\text{So } \langle p | \psi \rangle = A e^{-\frac{i}{\hbar} p x}$$

For the change of basis, this implies

$$|\psi\rangle = \int dp \underbrace{\langle p | \psi \rangle}_{\tilde{\psi}(p)} |p\rangle$$

$$\tilde{\psi}(p) = \langle p | \psi \rangle = \int \langle p | \underbrace{x | \psi \rangle}_{\psi(x)} dx = A \int e^{-\frac{i}{\hbar} px} \psi(x) dx$$

So,  $\tilde{\psi}(p)$  is the Fourier transform of  $\psi(x)$ .

(A) Find the factor A in transformation.

Operators in position space

$$\hat{O} |\psi\rangle = |\phi\rangle \rightarrow \text{In position space}$$

$$\langle x | \phi \rangle = \langle x | \hat{O} | \psi \rangle$$

We sometime use this notation

$$O \psi(x) \rightarrow \phi(x)$$

or

$$O \langle x | \psi \rangle = \langle x | \hat{O} | \psi \rangle$$

We use the  $\hat{O}$  for the operator in the original  
fl space and  $O$  for  $\cdot$  acting on  $\psi(x)$  i.e  
the representation in position.

Let's find  $P \hat{=} \langle x | \hat{P} | \psi \rangle$

$$\begin{aligned}\langle x | \hat{P} | \psi \rangle &= \langle x | \int dp p | \psi \rangle = \\ &= \int dp e^{i \frac{px}{\hbar}} \tilde{\psi}(p) p = \\ &= \int (-i \hbar \partial_x) e^{i \frac{px}{\hbar}} \tilde{\psi}(p) dp \\ &= -i \hbar \partial_x \psi(x)\end{aligned}$$

This means

$$P \psi(x) = -i \hbar \partial_x \psi(x)$$

Similarly, we can calculate the action  
of any operation.

$$\hat{K} = \frac{\hat{p}^2}{2m} : K \psi(x) = -\frac{\hbar^2}{2m} \partial_x^2 \psi(x)$$

$$\hat{H} = \frac{\hat{p}^2}{2m} + V(x) : H \psi(x) = \left( -\frac{\hbar^2}{2m} \partial_x^2 + V(x) \right) \psi(x)$$

(A)  $\rightarrow \hat{L} = \hat{R} \times \hat{p}$

$\rightarrow$  Schrödinger's equation

The evolution of the state is given by.

$$\frac{1}{i\hbar} |\psi(t)\rangle = -\frac{i}{\hbar} H(t) |\psi(t)\rangle$$

$$\frac{1}{i\hbar} \frac{d}{dt} |\psi(t)\rangle = -\frac{i}{\hbar} H(t) |\psi(t)\rangle$$

Now let's see how this looks like in the position basis.

$$\langle x | \frac{1}{i\hbar} \frac{d}{dt} |\psi(t)\rangle = -\frac{i}{\hbar} \langle x | H(t) |\psi(t)\rangle$$

$$\hat{H} = \frac{\hat{P}^2}{2m} + V(\hat{x})$$

$$\frac{d}{dt} \psi(x, t) = -\frac{i}{\hbar} \left[ \langle x | \frac{\hat{P}^2}{2m} |\psi(t)\rangle + \langle x | V(\hat{x}) |\psi(t)\rangle \right]$$

$$= -\frac{i}{\hbar} \left( -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} \psi(x, t) + V(x) \psi(x, t) \right)$$

$$\Rightarrow \frac{d}{dt} \psi(x, t) = \left( \frac{i\hbar}{2m} \frac{\partial^2}{\partial x^2} - \frac{i}{\hbar} V(x) \right) \psi(x, t)$$

Reminder:

$$|\psi(t)\rangle = \int_{-\infty}^{+\infty} \psi(x, t) |x\rangle dx$$

(A) Do the similar calculation in momentum space

→ Plane waves and wave packets

Take the state to be  $|\psi\rangle = |k\rangle$  at  $t=0$ .

Find the  $\psi(x, t)$  when there's no force (free particle)

$$\frac{d}{dt} \psi(k, t) = i\hbar \frac{\partial^2}{\partial k^2} \psi(k, t)$$

$$\frac{d}{dt} \psi(x, t) = \frac{i\hbar}{2m} \frac{\partial^2}{\partial x^2} \psi(x, t)$$

$$\psi(x, t) = \psi(x) \varphi(t) \Rightarrow$$

$$\frac{i}{\varphi(t)} \frac{d}{dt} \varphi(t) = -\frac{\hbar}{2m} \frac{1}{\psi(x)} \frac{\partial^2}{\partial x^2} \psi(x) = \omega$$

$$\varphi(t) = \varphi_0 e^{-i\omega t}, \quad \psi(x) = e^{\pm i\sqrt{\frac{2m}{\hbar}} \omega x} = e^{\pm ikx}$$

$$\psi(x, t) = A e^{i(kx - \omega t)} + B e^{-i(kx + \omega t)}$$

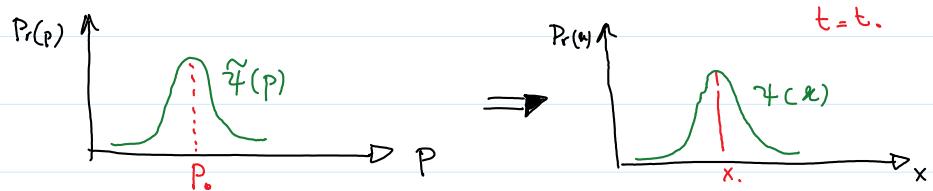
→ Solutions are plane waves moving to the left or right in time

(A) What's the dispersion relation?

(A) Find  $\tilde{\psi}(p, t)$ .

(A) What's the  $Pr(p)$  for this state? What's wrong with it?  
Does it change with time?  
What does such a wave function mean (say for electrons)?

Now, consider the following distribution.



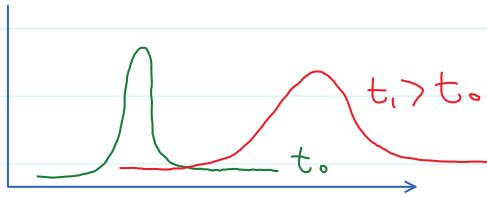
This is a combination of plane waves which is localized both in space & momentum.

(A) Take  $\psi(x) = e^{-\frac{(x-x_0)^2}{2\sigma^2}}$  for  $t=0$  and find

$$\text{a) } \tilde{\psi}(p, 0) \quad \text{b) } \psi(x, t)$$

c) Does this have the normalization problem of plane waves?

d) Show that the probability  $Pr(x)$  spreads out in time.



→ Probability current and conservation of Probability

$$\langle \bar{\psi}(t) | \psi(t) \rangle = \langle \bar{\psi}(0) | \hat{U}^\dagger \hat{U} | \psi(0) \rangle = \langle \bar{\psi}(0) | \psi(0) \rangle = 1$$

Equivalently, we can check that:  $\frac{d}{dt} \dots = 0$

$$\frac{d}{dt} \langle \bar{\psi}(t) | \psi(t) \rangle = \left( \frac{d}{dt} \langle \bar{\psi}(t) | \right) (\langle \psi(t) \rangle) +$$

$$\langle \bar{\psi}(t) | \left( \frac{d}{dt} \langle \psi(t) \rangle \right)$$

$$\text{We have: } \frac{d}{dt} \langle \bar{\psi}(t) | \psi(t) \rangle = -\frac{i}{\hbar} H \langle \bar{\psi}(t) | \psi(t) \rangle$$

$$\frac{d}{dt} \langle \bar{\psi}(t) | \psi(t) \rangle = \dots = 0$$

$\downarrow t \rightarrow 1 \sim 1 \sim$

$\hookrightarrow$  Check to see that if  $U$  was not unitary, this wouldn't be true.

Let's take a closer look at this in the position space:

$$\langle \psi(t) | \psi(t) \rangle = \int dx \left| \psi(x,t) \right|^2 = 1$$

$$i\hbar \frac{\partial \psi(u,t)}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi(x,t)}{\partial x^2} + V(u) \psi(x,t) \times \psi^*(u,t)$$

$$- \left( \dots \right)^* \times \psi(u,t)$$

$$\Rightarrow i\hbar \frac{\partial}{\partial t} \left( \underbrace{\psi^*(u,t) \psi(u,t)}_P \right) = -\frac{\hbar^2}{2m} \left( \psi^*(u,t) \frac{\partial^2}{\partial x^2} \psi(u,t) - \psi(x,t) \frac{\partial^2}{\partial x^2} \psi(x,t) \right)$$

$$P = \left| \psi(x,t) \right|^2$$

↓  
prob. density

We also introduce current density

$$J = \frac{i\hbar}{2m} \left[ \psi^*(u,t) \frac{\partial}{\partial x} \psi(u,t) - \psi(u,t) \frac{\partial}{\partial x} \psi^*(u,t) \right]$$

$$\Rightarrow \frac{\partial P(x,t)}{\partial t} + \frac{\partial}{\partial x} J = 0 \quad (\text{eq } *)$$

(A)

3D

a) Find  $P$  in 3 dimensional space:  $(P_x, P_y, P_z)$

b) II Schrödinger's eq. in 3D

b) // Schrödinger's eq. in 3D

c) .. the probability conservation above (eq \*)

in 3D.