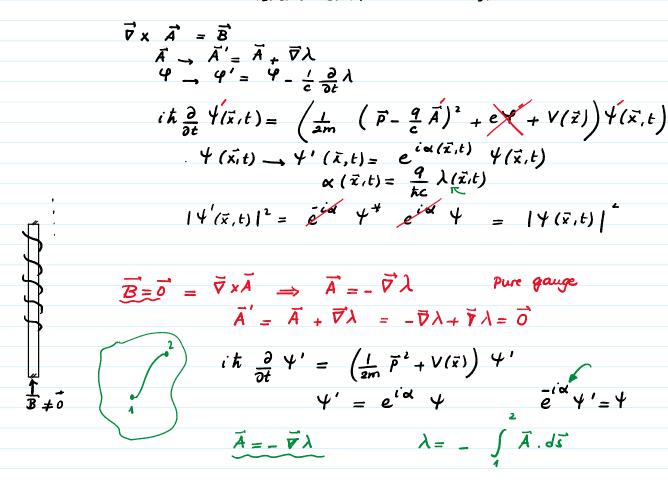
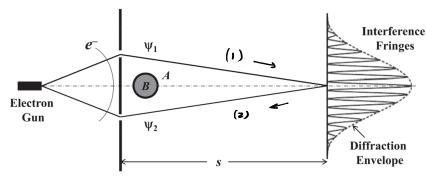
Monday, October 4, 2021 2:57 PM





$$\frac{d_{1} - d_{2}}{kc} = \frac{q}{kc} \left(\int_{1}^{\infty} \vec{A} \cdot d\vec{s} - \int_{2}^{\infty} \vec{A} \cdot d\vec{s} \right) = \frac{q}{kc} \int_{1}^{\infty} \left(\vec{\nabla} \times \vec{A} \right) \cdot d\vec{F}$$

$$= \frac{q}{kc} \int_{1}^{\infty} \vec{A} \cdot d\vec{s} = \frac{q}{kc} \int_{1}^{\infty} \left(\vec{\nabla} \times \vec{A} \right) \cdot d\vec{F}$$

$$= \frac{q}{kc} \int_{1}^{\infty} \vec{B} \cdot d\vec{F} = \frac{q}{kc} \oint_{1}^{\infty} \vec{A} \cdot d\vec{s}$$

$$H = H_{0} + H_{magn}$$

$$H_{0} = -\frac{k^{2}}{2m_{e}} \overrightarrow{\nabla}^{2} - \frac{e^{2}}{r}$$

$$E_{n} = -Ry \frac{1}{n^{2}}$$

$$H_{magn} = PB \frac{\overrightarrow{B} \cdot \overrightarrow{L}}{\hbar}$$

$$PB = \frac{e\hbar}{2m_{e}c}$$

$$B = Be_{3}$$

$$L_{3} | n l_{m} \rangle = \hbar m_{l} | n l_{m_{l}} \rangle$$

$$E = E_{n} + \Delta E_{m_{l}}$$

$$\Delta E_{m_{l}} = \mu_{B} B (m_{l} + 2m_{s})$$

$$M_{s} = \pm 1/2$$

المديل

$$\Delta E = \mu_{B} B \left(m_{\ell} + 2m_{s} \right) = \mu_{B} B \left(m_{\ell} \pm 1 \right)$$

$$l=1 \qquad m_{\ell} = 0 \qquad \begin{cases} + \mu_{B} B = \mu_{B} B(+1) \\ - \mu_{B} B = \mu_{B} B(-1) \end{cases}$$

$$m_{\ell} = 1 \qquad \begin{cases} \mu_{B} B \left(1 + 1 \right) = \mu_{B} B(2) \\ \mu_{B} B \left(1 + 1 \right) = \mu_{B} B(2) \end{cases}$$

$$m_{\ell} = 1 \qquad \begin{cases} \mu_{B} B \left(1 + 1 \right) = \mu_{B} B(2) \\ \mu_{B} B \left(-1 + 1 \right) = \mu_{B} B(0) \end{cases}$$

$$m_{\ell} = 1 \qquad \begin{cases} \mu_{B} B \left(-1 + 1 \right) = \mu_{B} B(-2) \\ \mu_{B} B \left(-1 - 1 \right) = \mu_{B} B(-2) \end{cases}$$

$$H_{magn} = \frac{\mu_{B}}{\hbar} B \left(\frac{L}{L} + 2S \right)$$

$$S = \frac{1}{2} \qquad m_{S} = \pm \frac{1}{2} \qquad down \downarrow$$

$$l=1$$

$$m_{\ell=-1}$$

$$m_{\ell=-1}$$

$$p_{\ell}=1$$

```
\left(\vec{p} + \frac{e}{c}\vec{A}\right)^2
\vec{\mu}_{J} = g_{J} \quad \frac{\mu_{B}}{\hbar} \quad \vec{J}
              \vec{J} = \vec{L} \qquad \vec{\mu}_{\vec{L}} = g_{\ell} \frac{r_{\ell}}{t} \vec{L} \qquad g_{\ell} = 1 \qquad g_{\ell} = 1
               \vec{J} = \vec{S} \qquad \vec{\mu}\vec{s} = g_s \quad \frac{\mu_B}{\pi} \vec{S} \qquad g_{s=2}
           \vec{L} = (l_x, l_y, l_z) [Li, Lj] = i \in ijk Lk
             \frac{L^{2} | l, m_{\ell} \rangle = \hbar^{2} l | l + 1 \rangle | l, m_{\ell} \rangle}{| l, m_{\ell} \rangle} = \frac{\hbar^{2} l | l + 1 \rangle}{| l, m_{\ell} \rangle} = \frac{l \leq m_{\ell} \leq l}{| l \leq m_{\ell} \leq l}
             \vec{S} = (S_x, S_y, S_z) \qquad [S_i, S_j] = i \in ijk S_k
              \vec{S}^2 \mid s, m_s \rangle = \hbar^2 s(s+i) \mid s, m_s \rangle
             Sz /s, ms>= t ms 1s, ms>
                                                                                                      البرن :
                         S = \frac{1}{2}
m_S = \pm \frac{1}{2}
                     |\uparrow\rangle \equiv |s = \frac{1}{2}, ms = +\frac{1}{2}\rangle up

|\psi\rangle \equiv |s = \frac{1}{2}, ms = -\frac{1}{2}\rangle down
              S^{2} | \uparrow \rangle = S^{2} | S = \frac{1}{2}, m_{S} = +\frac{1}{2} \rangle = \frac{\hbar^{2}}{2} \frac{1}{4} (\frac{1}{2} + 1) | \uparrow \rangle
              5^{2} |\uparrow\rangle = \frac{3}{4} t^{2} |\uparrow\rangle
          | S^2| \downarrow \rangle = \frac{3}{4} h^2 | \downarrow \rangle
                  S_2 | S = \frac{1}{2}, m_S = +\frac{1}{2} \rangle = +\frac{1}{2} | S = \frac{1}{2}, m_S = +\frac{1}{2} \rangle
                                S_{z} | \uparrow \rangle = + \frac{\hbar}{2} | \uparrow \rangle
S_{z} | \downarrow \rangle = -\frac{\hbar}{2} | \downarrow \rangle
                  L_{\pm} | l, m_{\ell} \rangle = \hbar \sqrt{l(l+1) - m_{\ell}(m_{\ell} \pm 1)} | l, m_{\ell} \pm 1 \rangle
                                                                                    [S_i, S_j] = i \in ijk S_k
              S_{\pm} = S_{x} \pm i S_{x}
                      S_{\pm} |s,ms\rangle = \hbar \sqrt{s(s+1)} - ms (ms\pm 1) |s,ms\pm 1\rangle
         a) S_+ \stackrel{\uparrow}{\downarrow} = h \sqrt{\frac{1}{2}(\frac{1}{2}+1)} \stackrel{\downarrow}{\downarrow} (\frac{1}{2}+1) | \dots \rangle = 0
                                |s=\frac{1}{2}|ms=+\frac{1}{2}\rangle
          S + \frac{11}{2} = \frac{1}{2} \left( \frac{1}{2} + 1 \right) + \frac{1}{2} \left( -\frac{1}{2} + 1 \right) \qquad \left| \frac{1}{2} - \frac{1}{2} + 1 \right| 
                                  \left| S = \frac{1}{2}, m_{S} = -\frac{1}{2} \right\rangle
                                 S_{+} | \downarrow \rangle = \pi | \uparrow \rangle
```

c)
$$S = |\uparrow\rangle = |t\rangle$$

d) $S = |\downarrow\rangle = 0$

$$S_{+} = S_{x+i} S_{y}$$

$$S_{-} = S_{x-i} S_{y}$$

$$S_{+} = \frac{1}{2} (S_{+} + S_{-})$$

$$S_{+} = \frac{1}{2} (S_{+} +$$

$$S_{i} = \begin{cases} \langle \uparrow | S_{i} | \uparrow \rangle & \langle \uparrow | S_{i} | \downarrow \rangle \\ \langle \downarrow | S_{i} | \uparrow \rangle & \langle \downarrow | S_{i} | \downarrow \rangle \\ \langle \downarrow | S_{x} | \uparrow \rangle & \langle \uparrow | S_{x} | \downarrow \rangle \\ \langle \downarrow | S_{x} | \uparrow \rangle & \langle \downarrow | S_{x} | \downarrow \rangle \\ \langle \uparrow | \downarrow \rangle = \langle \downarrow | \uparrow \rangle = 0 \\ \langle \downarrow | \downarrow \rangle = 1 \end{cases}$$

$$\langle 1|S_{x}|1\rangle = \frac{\hbar}{2} \quad \langle 1|1\rangle = 0$$

$$\langle 1|S_{x}|1\rangle = \frac{\hbar}{2} \quad \langle 1|1\rangle = \frac{\hbar}{2}$$

$$\langle 1|S_{x}|1\rangle = 0 \quad S_{x} = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$S_{y} = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad S_{z} = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$S_{z} = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad S_{z} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$S_{x} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad S_{z} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad S_{z} = \begin{pmatrix} 0 & -i \\ 0 & -1 \end{pmatrix}$$

$$S_{x} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad S_{z} = \begin{pmatrix} 0 & -i \\ 0 & -1 \end{pmatrix} \quad S_{z} = \begin{pmatrix} 0 & -i \\ 0 & -1 \end{pmatrix}$$

$$S_{x} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad S_{z} = \begin{pmatrix} 0 & -i \\ 0 & -1 \end{pmatrix} \quad S_{z} = \begin{pmatrix} 0 & -i \\ 0 & -1 \end{pmatrix}$$