

# Appendix 4

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## Dyadic Analysis\*

### DEFINITIONS

Vector  $\mathbf{d}'$  is a linear vector function of vector  $\mathbf{d}$  when the following relationships hold:

$$\begin{aligned}d'_x &= a_{xx}d_x + a_{xy}d_y + a_{xz}d_z \\d'_y &= a_{yx}d_x + a_{yy}d_y + a_{yz}d_z \\d'_z &= a_{zx}d_x + a_{zy}d_y + a_{zz}d_z.\end{aligned}\tag{A4.1}$$

These relationships can be represented in more compact form by means of the matrix notation

$$\mathbf{d}' = \bar{\bar{\mathbf{a}}}\cdot\mathbf{d}.\tag{A4.2}$$

The matrix operator itself can be expressed in terms of dyads as

$$\begin{aligned}\bar{\bar{\mathbf{a}}} &= a_{xx}\mathbf{u}_x\mathbf{u}_x + a_{xy}\mathbf{u}_x\mathbf{u}_y + a_{xz}\mathbf{u}_x\mathbf{u}_z + a_{yx}\mathbf{u}_y\mathbf{u}_x + a_{yy}\mathbf{u}_y\mathbf{u}_y \\ &+ a_{yz}\mathbf{u}_y\mathbf{u}_z + a_{zx}\mathbf{u}_z\mathbf{u}_x + a_{zy}\mathbf{u}_z\mathbf{u}_y + a_{zz}\mathbf{u}_z\mathbf{u}_z\end{aligned}\tag{A4.3}$$

provided, by convention,  $\mathbf{ab}\cdot\mathbf{c}$  stands for  $\mathbf{a}(\mathbf{b}\cdot\mathbf{c})$ . The symbol  $\mathbf{ab}$  is called a *dyad*, and a sum of dyads such as  $\bar{\bar{\mathbf{a}}}$  is a *dyadic*. Also by convention,  $\mathbf{c}\cdot\mathbf{ab}$  stands for  $(\mathbf{c}\cdot\mathbf{a})\mathbf{b}$ , so that the dot product of a dyad and a vector is now defined for  $\mathbf{ab}$  acting as both a prefactor and a postfactor. The writing of  $\bar{\bar{\mathbf{a}}}$  in “nonion” form, as shown above, is rather cumbersome, and one often prefers to use the form

$$\begin{aligned}\bar{\bar{\mathbf{a}}} &= (a_{xx}\mathbf{u}_x + a_{yx}\mathbf{u}_y + a_{zx}\mathbf{u}_z)\mathbf{u}_x + (a_{xy}\mathbf{u}_x + a_{yy}\mathbf{u}_y + a_{zy}\mathbf{u}_z)\mathbf{u}_y \\ &+ (a_{xz}\mathbf{u}_x + a_{yz}\mathbf{u}_y + a_{zz}\mathbf{u}_z)\mathbf{u}_z = \mathbf{a}'_x\mathbf{u}_x + \mathbf{a}'_y\mathbf{u}_y + \mathbf{a}'_z\mathbf{u}_z\end{aligned}\tag{A4.4}$$

where the  $\mathbf{a}'$  are the column vectors of the matrix of  $\bar{\bar{\mathbf{a}}}$ . Alternatively,

$$\begin{aligned}\bar{\bar{\mathbf{a}}} &= \mathbf{u}_x(a_{xx}\mathbf{u}_x + a_{xy}\mathbf{u}_y + a_{xz}\mathbf{u}_z) + \mathbf{u}_y(a_{yx}\mathbf{u}_x + a_{yy}\mathbf{u}_y + a_{yz}\mathbf{u}_z) \\ &+ \mathbf{u}_z(a_{zx}\mathbf{u}_x + a_{zy}\mathbf{u}_y + a_{zz}\mathbf{u}_z) = \mathbf{u}_x\mathbf{a}_x + \mathbf{u}_y\mathbf{a}_y + \mathbf{u}_z\mathbf{a}_z,\end{aligned}\tag{A4.5}$$

\*Professor Lindell has been kind enough to check this appendix, make corrections, and suggest additional formulas.

where the  $\mathbf{a}$  are the row vectors of the matrix of  $\bar{\bar{a}}$ . It is obvious that  $\bar{\bar{a}} \cdot \mathbf{d}$  is, in general, different from  $\mathbf{d} \cdot \bar{\bar{a}}$ . In other words, the order in which  $\bar{\bar{a}}$  and  $\mathbf{d}$  appear should be carefully respected.  $\bar{\bar{a}} \cdot \mathbf{d}$  is equal to  $\mathbf{d} \cdot \bar{\bar{a}}$  only when the dyadic is symmetric (i.e., when  $a_{ik} = a_{ki}$ ). The *transpose* of  $\bar{\bar{a}}$  is a dyadic  $\bar{\bar{a}}^t$  such that  $\bar{\bar{a}} \cdot \mathbf{d}$  is equal to  $\mathbf{d} \cdot \bar{\bar{a}}^t$ . One may easily check that the transpose is obtained by an interchange of rows and columns. More precisely,

$$\bar{\bar{a}}^t = \mathbf{a}_x \mathbf{u}_x + \mathbf{a}_y \mathbf{u}_y + \mathbf{a}_z \mathbf{u}_z = \mathbf{u}_x \mathbf{a}'_x + \mathbf{u}_y \mathbf{a}'_y + \mathbf{u}_z \mathbf{a}'_z. \quad (\text{A4.6})$$

The *trace of the dyadic* is the sum of its diagonal terms. Thus,

$$\text{tr } \bar{\bar{a}} = a_{xx} + a_{yy} + a_{zz}. \quad (\text{A4.7})$$

The trace is a scalar (i.e., it is invariant with respect to orthogonal transformations of the base vectors). The trace of  $\mathbf{ab}$  is  $\mathbf{a} \cdot \mathbf{b}$ . Among dyadics endowed with special properties we note

1. The *unitary dyadic*, which represents a pure rotation. The determinant of its elements is equal to 1.
2. The *identity dyadic*

$$\bar{\bar{I}} = \mathbf{u}_x \mathbf{u}_x + \mathbf{u}_y \mathbf{u}_y + \mathbf{u}_z \mathbf{u}_z. \quad (\text{A4.8})$$

Clearly,

$$\bar{\bar{I}} \cdot \mathbf{d} = \mathbf{d} \cdot \bar{\bar{I}} = \mathbf{d}. \quad (\text{A4.9})$$

3. The *symmetric dyadic*, characterized by  $a_{ik} = a_{ki}$ , for which  $\bar{\bar{a}}^t = \bar{\bar{a}}$ . The dyadic  $\mathbf{ab}$  is symmetric when  $\mathbf{a} \times \mathbf{b} = 0$ . Further,

$$\bar{\bar{a}} \cdot \mathbf{d} = \mathbf{d} \cdot \bar{\bar{a}}. \quad (\text{A4.10})$$

4. The *antisymmetric dyadic*, characterized by  $a_{ik} = -a_{ki}$ . For such a dyadic  $\bar{\bar{a}}^t = -\bar{\bar{a}}$ , and

$$\bar{\bar{a}} \cdot \mathbf{d} = -\mathbf{d} \cdot \bar{\bar{a}}. \quad (\text{A4.11})$$

The diagonal elements are zero, and there are only three distinct components. The dyadic can always be written in terms of  $\bar{\bar{I}}$  and a suitable vector  $\mathbf{b}$  as

$$\begin{aligned} \bar{\bar{a}} &= -b_z \mathbf{u}_x \mathbf{u}_y + b_y \mathbf{u}_x \mathbf{u}_z + b_z \mathbf{u}_y \mathbf{u}_x \\ &\quad - b_x \mathbf{u}_y \mathbf{u}_z - b_y \mathbf{u}_z \mathbf{u}_x + b_x \mathbf{u}_z \mathbf{u}_y, \\ &= \bar{\bar{I}} \times \mathbf{b}, \end{aligned} \quad (\text{A4.12})$$

where the *skew product* is the dyad

$$(\mathbf{bc}) \times \mathbf{d} = \mathbf{b}(\mathbf{c} \times \mathbf{d}). \quad (\text{A4.13})$$

The antisymmetric  $\bar{\bar{a}}$  can also be expressed as

$$\bar{\bar{a}} = \mathbf{cb} - \mathbf{bc}. \quad (\text{A4.14})$$

5. The *reflection dyadic*

$$\bar{\bar{r}}_f(\mathbf{u}) = \bar{\bar{I}} - 2\mathbf{u}\mathbf{u}, \quad (\text{A4.15})$$

where  $\mathbf{u}$  is a (real) unit vector. Applied to the position vector  $\mathbf{r}$ , it performs a reflection with respect to a plane perpendicular to  $\mathbf{u}$ .

 6. The *rotation dyadic*

$$\bar{\bar{r}}_r(\mathbf{u}) = \mathbf{u}\mathbf{u} + \sin \theta (\mathbf{u} \times \bar{\bar{I}}) + \cos \theta (\bar{\bar{I}} - \mathbf{u}\mathbf{u}). \quad (\text{A4.16})$$

Applied to a vector, it performs a rotation by an angle  $\theta$  in the right-hand direction around the direction of  $\mathbf{u}$ .

The elements of a dyadic may be complex (a case in point is the free-space dyadic discussed in Chapter 7). It then becomes useful to introduce concepts such as the *Hermitian dyadic* ( $a_{ik} = a_{ki}^*$ ), or the *anti-Hermitian dyadic* ( $a_{ik} = -a_{ki}^*$ ). Useful *products of dyads* are defined as follows:

$$(\mathbf{ab}) \cdot (\mathbf{cd}) = \mathbf{a}(\mathbf{b} \cdot \mathbf{c})\mathbf{d} \quad (\text{the direct product, a dyad}). \quad (\text{A4.17})$$

$$(\mathbf{ab}) : (\mathbf{cd}) = (\mathbf{a} \cdot \mathbf{c})(\mathbf{b} \cdot \mathbf{d}) \quad (\text{the double product, a scalar}). \quad (\text{A4.18})$$

$$(\mathbf{ab}) \overset{\times}{\times} (\mathbf{cd}) = (\mathbf{a} \times \mathbf{c})(\mathbf{b} \times \mathbf{d}) \quad (\text{the double cross-product, a dyad}). \quad (\text{A4.19})$$

$$(\mathbf{ab}) \overset{\times}{\cdot} (\mathbf{cd}) = (\mathbf{a} \times \mathbf{c})(\mathbf{b} \cdot \mathbf{d}) \quad (\text{a vector}). \quad (\text{A4.20})$$

$$(\mathbf{ab}) \overset{\cdot}{\times} (\mathbf{cd}) = (\mathbf{a} \cdot \mathbf{c})(\mathbf{b} \times \mathbf{d}) \quad (\text{a vector}). \quad (\text{A4.21})$$

## General Multiplicative Relationships

$$(\mathbf{b} \cdot \bar{\bar{a}}) \cdot \mathbf{c} = \mathbf{b} \cdot (\bar{\bar{a}} \cdot \mathbf{c}) = \mathbf{b} \cdot \bar{\bar{a}} \cdot \mathbf{c} \quad (\text{A4.22})$$

$$(\mathbf{b} \times \mathbf{c}) \cdot \bar{\bar{a}} = \mathbf{b} \cdot (\mathbf{c} \times \bar{\bar{a}}) = -\mathbf{c} \cdot (\mathbf{b} \times \bar{\bar{a}}) \quad (\text{A4.23})$$

$$(\bar{\bar{a}} \times \mathbf{b}) \cdot \mathbf{c} = \bar{\bar{a}} \cdot (\mathbf{b} \times \mathbf{c}) = -(\bar{\bar{a}} \times \mathbf{c}) \cdot \mathbf{b} \quad (\text{but not } (\bar{\bar{a}} \cdot \mathbf{b}) \times \mathbf{c}) \quad (\text{A4.24})$$

$$(\mathbf{b} \times \bar{\bar{a}}) \cdot \mathbf{c} = \mathbf{b} \times (\bar{\bar{a}} \cdot \mathbf{b}) \quad (\text{A4.25})$$

$$(\mathbf{b} \cdot \bar{\bar{a}}) \times \mathbf{c} = \mathbf{b} \cdot (\bar{\bar{a}} \times \mathbf{c}) \quad (\text{A4.26})$$

$$(\mathbf{b} \times \bar{\bar{a}}) \times \mathbf{c} = \mathbf{b} \times (\bar{\bar{a}} \times \mathbf{c}) = \mathbf{b} \times \bar{\bar{a}} \times \mathbf{c} \quad (\text{A4.27})$$

$$\mathbf{b} \times (\mathbf{c} \times \bar{\bar{a}}) = \mathbf{c}(\mathbf{b} \cdot \bar{\bar{a}}) - \bar{\bar{a}}(\mathbf{b} \cdot \mathbf{c}) \quad (\text{A4.28})$$

$$(\mathbf{bc} - \mathbf{cb}) \cdot \mathbf{d} = (\mathbf{c} \times \mathbf{b}) \times \mathbf{d} \quad (\text{A4.29})$$

$$(\mathbf{c} \cdot \bar{\bar{a}}) \cdot \bar{\bar{b}} = \mathbf{c} \cdot (\bar{\bar{a}} \cdot \bar{\bar{b}}) = \mathbf{c} \cdot \bar{\bar{a}} \cdot \bar{\bar{b}} \quad (\text{A4.30})$$

$$(\bar{\bar{a}} \cdot \bar{\bar{b}}) \cdot \mathbf{c} = \bar{\bar{a}} \cdot (\bar{\bar{b}} \cdot \mathbf{c}) = \bar{\bar{a}} \cdot \bar{\bar{b}} \cdot \mathbf{c} \quad (\text{A4.31})$$

$$(\mathbf{c} \times \bar{\bar{a}}) \cdot \bar{\bar{b}} = \mathbf{c} \times (\bar{\bar{a}} \cdot \bar{\bar{b}}) = \mathbf{c} \times \bar{\bar{a}} \cdot \bar{\bar{b}} \quad (\text{A4.32})$$

$$(\bar{\bar{a}} \cdot \bar{\bar{b}}) \times \mathbf{c} = \bar{\bar{a}} \cdot (\bar{\bar{b}} \times \mathbf{c}) = \bar{\bar{a}} \cdot \bar{\bar{b}} \times \mathbf{c} \quad (\text{A4.33})$$

$$(\bar{\bar{a}} \times \mathbf{c}) \cdot \bar{\bar{b}} = \bar{\bar{a}} \cdot (\mathbf{c} \times \bar{\bar{b}}) \quad (\text{A4.34})$$

$$\mathbf{b} \cdot \bar{\bar{a}} \cdot \mathbf{c} = \mathbf{c} \cdot \bar{\bar{a}}^t \cdot \mathbf{b} \quad (\text{A4.35})$$

$$\bar{\bar{a}} \cdot (\bar{\bar{b}} \cdot \bar{\bar{c}}) = (\bar{\bar{a}} \cdot \bar{\bar{b}}) \cdot \bar{\bar{c}}. \quad (\text{A4.36})$$

The identity dyadic satisfies the following relationships:

$$(\bar{\bar{I}} \times \mathbf{b}) \cdot \mathbf{c} = \mathbf{b} \cdot (\bar{\bar{I}} \times \mathbf{c}) = \mathbf{b} \times \mathbf{c} \quad (\text{A4.37})$$

$$(\bar{\bar{I}} \times \mathbf{b}) \cdot \bar{\bar{a}} = \mathbf{b} \times \bar{\bar{a}} = (\mathbf{b} \times \bar{\bar{I}}) \cdot \bar{\bar{a}} \quad (\text{A4.38})$$

$$\bar{\bar{I}} \times (\mathbf{b} \times \mathbf{c}) = \mathbf{cb} - \mathbf{bc}. \quad (\text{A4.39})$$

## DIFFERENTIAL RELATIONSHIPS

### Differentiation with Respect to a Parameter

$$\frac{d}{dt}(f\bar{\bar{a}}) = \frac{df}{dt}\bar{\bar{a}} + f\frac{d\bar{\bar{a}}}{dt} \quad (\text{A4.40})$$

$$\frac{d}{dt}(\bar{\bar{a}} \cdot \mathbf{b}) = \frac{d\bar{\bar{a}}}{dt} \cdot \mathbf{b} + \bar{\bar{a}} \cdot \frac{d\mathbf{b}}{dt} \quad (\text{A4.41})$$

$$\frac{d}{dt}(\bar{\bar{a}} \times \mathbf{b}) = \frac{d\bar{\bar{a}}}{dt} \times \mathbf{b} + \bar{\bar{a}} \times \frac{d\mathbf{b}}{dt} \quad (\text{A4.42})$$

$$\frac{d}{dt}(\bar{\bar{a}} \cdot \bar{\bar{b}}) = \frac{d\bar{\bar{a}}}{dt} \cdot \bar{\bar{b}} + \bar{\bar{a}} \cdot \frac{d\bar{\bar{b}}}{dt}. \quad (\text{A4.43})$$

### Basic Differential Operators

The action of a linear operator  $\mathcal{L}$  on a dyadic is defined by the formula

$$\mathcal{L}\bar{\bar{a}} = (\mathcal{L}\mathbf{a}'_x)\mathbf{u}_x + (\mathcal{L}\mathbf{a}'_y)\mathbf{u}_y + (\mathcal{L}\mathbf{a}'_z)\mathbf{u}_z. \quad (\text{A4.44})$$

In particular,

$$\begin{aligned} \text{div } \bar{\bar{a}} &= \nabla \cdot \bar{\bar{a}} = (\text{div } \mathbf{a}'_x)\mathbf{u}_x + (\text{div } \mathbf{a}'_y)\mathbf{u}_y + (\text{div } \mathbf{a}'_z)\mathbf{u}_z \\ &= \frac{\partial \mathbf{a}_x}{\partial x} + \frac{\partial \mathbf{a}_y}{\partial y} + \frac{\partial \mathbf{a}_z}{\partial z} \end{aligned} \quad (\text{A4.45})$$

$$\begin{aligned} \text{curl } \bar{\bar{a}} &= \nabla \times \bar{\bar{a}} = (\text{curl } \mathbf{a}'_x)\mathbf{u}_x + (\text{curl } \mathbf{a}'_y)\mathbf{u}_y + (\text{curl } \mathbf{a}'_z)\mathbf{u}_z \\ &= \mathbf{u}_x \left( \frac{\partial \mathbf{a}_z}{\partial y} - \frac{\partial \mathbf{a}_y}{\partial z} \right) + \mathbf{u}_y \left( \frac{\partial \mathbf{a}_x}{\partial z} - \frac{\partial \mathbf{a}_z}{\partial x} \right) + \mathbf{u}_z \left( \frac{\partial \mathbf{a}_y}{\partial x} - \frac{\partial \mathbf{a}_x}{\partial y} \right) \end{aligned} \quad (\text{A4.46})$$

$$\nabla^2 \bar{\bar{a}} = \frac{\partial^2 \bar{\bar{a}}}{\partial x^2} + \frac{\partial^2 \bar{\bar{a}}}{\partial y^2} + \frac{\partial^2 \bar{\bar{a}}}{\partial z^2} = \text{grad div } \bar{\bar{a}} - \text{curl curl } \bar{\bar{a}}. \quad (\text{A4.47})$$

Also

$$\begin{aligned}\text{grad } \mathbf{a} &= \nabla \mathbf{a} = \mathbf{u}_x \frac{\partial \mathbf{a}}{\partial x} + \mathbf{u}_y \frac{\partial \mathbf{a}}{\partial y} + \mathbf{u}_z \frac{\partial \mathbf{a}}{\partial z} \\ &= \text{grad } a_x \mathbf{u}_x + \text{grad } a_y \mathbf{u}_y + \text{grad } a_z \mathbf{u}_z\end{aligned}\quad (\text{A4.48})$$

$$\mathbf{a} \text{ grad} = \mathbf{a} \nabla = \mathbf{a} \mathbf{u}_x \frac{\partial}{\partial x} + \mathbf{a} \mathbf{u}_y \frac{\partial}{\partial y} + \mathbf{a} \mathbf{u}_z \frac{\partial}{\partial z}.\quad (\text{A4.49})$$

## Derived Relationships

$$\text{grad}(\mathbf{b} \times \mathbf{c}) = (\text{grad } \mathbf{b}) \times \mathbf{c} - (\text{grad } \mathbf{c}) \times \mathbf{b}\quad (\text{A4.50})$$

$$\text{grad}(f\mathbf{b}) = (\text{grad } f)\mathbf{b} + f \text{ grad } \mathbf{b} \quad (f \text{ is any scalar function})\quad (\text{A4.51})$$

$$(\mathbf{b} \cdot \text{grad})\bar{a} = b_x \frac{\partial \bar{a}}{\partial x} + b_y \frac{\partial \bar{a}}{\partial y} + b_z \frac{\partial \bar{a}}{\partial z}\quad (\text{A4.52})$$

$$d\mathbf{r} \cdot \text{grad } \mathbf{a} = d\mathbf{a}\quad (\text{A4.53})$$

$$\text{div}(\mathbf{bc}) = (\text{div } \mathbf{b})\mathbf{c} + \mathbf{b} \cdot \text{grad } \mathbf{c}\quad (\text{A4.54})$$

$$\text{div } \text{curl } \bar{a} = 0\quad (\text{A4.55})$$

$$\text{div}(f\bar{a}) = \text{grad } f \cdot \bar{a} + f \text{ div } \bar{a}\quad (\text{A4.56})$$

$$\text{div}(\bar{a} \cdot \mathbf{b}) = (\text{div } \bar{a}) \cdot \mathbf{b} + \text{tr}(\bar{a}^t \cdot \text{grad } \mathbf{b})\quad (\text{A4.57})$$

$$\text{div}(\mathbf{b} \times \bar{a}) = (\text{curl } \mathbf{b}) \cdot \bar{a} - \mathbf{b} \cdot \text{curl } \bar{a}\quad (\text{A4.58})$$

$$\text{div}(\mathbf{bc} - \mathbf{cb}) = \text{curl}(\mathbf{c} \times \mathbf{b})\quad (\text{A4.59})$$

$$\text{div}(f\bar{I}) = \text{grad } f\quad (\text{A4.60})$$

$$\text{div}(\bar{I} \times \mathbf{a}) = \text{curl } \mathbf{a}\quad (\text{A4.61})$$

$$\text{curl}(\mathbf{bc}) = (\text{curl } \mathbf{b})\mathbf{c} - \mathbf{b} \times \text{grad } \mathbf{c}\quad (\text{A4.62})$$

$$\text{curl } \text{grad } \mathbf{a} = 0\quad (\text{A4.63})$$

$$\text{curl}(f\bar{a}) = \text{grad } f \times \bar{a} + f \text{ curl } \bar{a}\quad (\text{A4.64})$$

$$\text{curl}(f\bar{I}) = \text{grad } f \times \bar{I}\quad (\text{A4.65})$$

$$\text{curl}(\bar{a} \times \mathbf{b}) = \text{curl } \bar{a} \times \mathbf{b} - \text{grad } \mathbf{b} \times \bar{a}\quad (\text{A4.66})$$

$$\text{curl } \text{curl}(f\bar{I}) = \text{curl}(\text{grad } f \times \bar{I}) = \text{grad } \text{grad } f - \bar{I} \nabla^2 f.\quad (\text{A4.67})$$

## INTEGRAL RELATIONSHIPS

The integral relationships of vector analysis have their equivalent in dyadic analysis. The most important examples are

$$\int_M^N d\mathbf{c} \cdot \text{grad } \mathbf{a} = \mathbf{a}(N) - \mathbf{a}(M)\quad (\text{A4.68})$$

$$\int_c \mathbf{d}\mathbf{c} \mathbf{a} = \int_S \mathbf{u}_n \times \text{grad } \mathbf{a} dS, \quad (\text{A4.69})$$

where the contour is described in the positive sense with respect to  $\mathbf{u}_n$ .

$$\int_c \mathbf{d}\mathbf{c} \cdot \bar{\mathbf{a}} = \int_S \mathbf{u}_n \cdot \text{curl } \bar{\mathbf{a}} dS \quad (\text{A4.70})$$

$$\int_V \text{grad } \mathbf{a} dV = \int_S \mathbf{u}_n \mathbf{a} dS \quad (\text{A4.71})$$

$$\int_V \text{div } \bar{\mathbf{a}} dV = \int_S \mathbf{u}_n \cdot \bar{\mathbf{a}} dS \quad (\text{A4.72})$$

$$\int_V \text{curl } \bar{\mathbf{a}} dV = \int_S \mathbf{u}_n \times \bar{\mathbf{a}} dS \quad (\text{A4.73})$$

$$\int_V [\mathbf{b} \cdot \text{grad div } \bar{\mathbf{a}} - (\text{grad div } \mathbf{b}) \cdot \bar{\mathbf{a}}] dV = \int_S [(\mathbf{u}_n \cdot \mathbf{b}) \text{div } \bar{\mathbf{a}} - \text{div } \mathbf{b} (\mathbf{u}_n \cdot \bar{\mathbf{a}})] dS \quad (\text{A4.74})$$

$$\begin{aligned} \int_V [(\text{curl curl } \mathbf{b}) \cdot \bar{\mathbf{a}} - \mathbf{b} \cdot \text{curl curl } \bar{\mathbf{a}}] dV &= \int_S [(\mathbf{u}_n \times \mathbf{b}) \cdot \text{curl } \bar{\mathbf{a}} + (\mathbf{u}_n \times \text{curl } \mathbf{b}) \cdot \bar{\mathbf{a}}] dS \\ &= \int_S [\mathbf{u}_n \cdot (\mathbf{b} \times \text{curl } \bar{\mathbf{a}}) + \mathbf{u}_n \cdot (\text{curl } \mathbf{b} \times \bar{\mathbf{a}})] dS \end{aligned} \quad (\text{A4.75})$$

$$\begin{aligned} \int_V [\mathbf{b} \cdot \nabla^2 \bar{\mathbf{a}} - (\nabla^2 \mathbf{b}) \cdot \bar{\mathbf{a}}] dV &= \int_S [(\mathbf{u}_n \cdot \mathbf{b}) \text{div } \bar{\mathbf{a}} - \text{div } \mathbf{b} (\mathbf{u}_n \cdot \bar{\mathbf{a}}) \\ &\quad + \mathbf{u}_n \cdot (\mathbf{b} \times \text{curl } \bar{\mathbf{a}}) + \mathbf{u}_n \cdot (\text{curl } \mathbf{b} \times \bar{\mathbf{a}})] dS \end{aligned} \quad (\text{A4.76})$$

$$\int_V (\mathbf{a} \nabla^2 f - f \nabla^2 \mathbf{a}) dV = \int_S \mathbf{u}_n \cdot (\text{grad } f \mathbf{a} - f \text{grad } \mathbf{a}) dS. \quad (\text{A4.77})$$

## RELATIONSHIPS IN CYLINDRICAL COORDINATES

Dyadic  $\bar{\mathbf{a}}$  can be written as

$$\bar{\mathbf{a}} = \mathbf{a}'_r \mathbf{u}_r + \mathbf{a}'_\varphi \mathbf{u}_\varphi + \mathbf{a}'_z \mathbf{u}_z = \mathbf{u}_r \mathbf{a}_r + \mathbf{u}_\varphi \mathbf{a}_\varphi + \mathbf{u}_z \mathbf{a}_z.$$

The basic differential operators are then:

$$\begin{aligned} \text{grad } \mathbf{a} &= \left( \text{grad } a_r - \frac{a_\varphi \mathbf{u}_\varphi}{r} \right) \mathbf{u}_r + \left( \text{grad } a_\varphi + \frac{a_r \mathbf{u}_\varphi}{r} \right) \mathbf{u}_\varphi + \text{grad } a_z \mathbf{u}_z \\ &= \mathbf{u}_r \frac{\partial \mathbf{a}}{\partial r} + \mathbf{u}_\varphi \frac{1}{r} \frac{\partial \mathbf{a}}{\partial \varphi} + \mathbf{u}_z \frac{\partial \mathbf{a}}{\partial z} \end{aligned} \quad (\text{A4.78})$$

$$\begin{aligned} \text{div } \bar{\mathbf{a}} &= \left( \text{div } \mathbf{a}'_r - \frac{a_\varphi \varphi}{r} \right) \mathbf{u}_r + \left( \text{div } \mathbf{a}'_\varphi + \frac{a_\varphi r}{r} \right) \mathbf{u}_\varphi + (\text{div } \mathbf{a}'_z) \mathbf{u}_z \\ &= \frac{1}{r} \mathbf{a}_r + \frac{\partial \mathbf{a}}{\partial r} + \frac{1}{r} \frac{\partial \mathbf{a}_\varphi}{\partial \varphi} + \frac{\partial \mathbf{a}_z}{\partial z} \end{aligned} \quad (\text{A4.79})$$

$$\begin{aligned}\text{curl } \bar{\bar{a}} &= \left( \text{curl } \mathbf{a}'_r + \frac{\mathbf{a}'_\varphi \times \mathbf{u}_\varphi}{r} \right) \mathbf{u}_r + \left( \text{curl } \mathbf{a}'_\varphi - \frac{\mathbf{a}'_r \times \mathbf{u}_\varphi}{r} \right) \mathbf{u}_\varphi + \text{curl } \mathbf{a}'_z \mathbf{u}_z \\ &= \mathbf{u}_r \left( \frac{1}{r} \frac{\partial \mathbf{a}_z}{\partial \varphi} - \frac{\partial \mathbf{a}_\varphi}{\partial z} \right) + \mathbf{u}_\varphi \left( \frac{\partial \mathbf{a}_r}{\partial z} - \frac{\partial \mathbf{a}_z}{\partial r} \right) + \mathbf{u}_z \left( \frac{\mathbf{a}_\varphi}{r} + \frac{\partial \mathbf{a}_\varphi}{\partial r} - \frac{1}{r} \frac{\partial \mathbf{a}_r}{\partial \varphi} \right).\end{aligned}\quad (\text{A4.80})$$

In particular:

$$\text{grad } \mathbf{u}_r = \frac{\mathbf{u}_\varphi \mathbf{u}_\varphi}{r} \quad (\text{A4.81})$$

$$\text{grad } \mathbf{u}_\varphi = -\frac{\mathbf{u}_\varphi \mathbf{u}_r}{r} \quad (\text{A4.82})$$

$$\text{grad } \mathbf{u}_z = 0 \quad (\text{A4.83})$$

$$\text{grad}(r\mathbf{u}_r) = \mathbf{u}_r \mathbf{u}_r + \mathbf{u}_\varphi \mathbf{u}_\varphi = \bar{\bar{I}} - \mathbf{u}_z \mathbf{u}_z. \quad (\text{A4.84})$$

Note that the dyadic operators expressed in terms of the row vectors  $\mathbf{a}$  are identical with their vector counterparts provided bars are put above scalar projections to transform them into row vectors, and provided the unit vectors are used as *prefactors*. This simple rule, which is also valid in spherical coordinates, allows one to write composite operators such as grad div simply by referring to the vector formula. For example:

$$\nabla^2 \bar{\bar{a}} = \mathbf{u}_r \left( \nabla^2 \mathbf{a}_r - \frac{\mathbf{a}_r}{r^2} - \frac{2}{r^2} \frac{\partial \mathbf{a}_\varphi}{\partial \varphi} \right) + \mathbf{u}_\varphi \left( \nabla^2 \mathbf{a}_\varphi - \frac{\mathbf{a}_\varphi}{r^2} + \frac{2}{r^2} \frac{\partial \mathbf{a}_r}{\partial \varphi} \right) + \mathbf{u}_z \nabla^2 \mathbf{a}_z. \quad (\text{A4.85})$$

## RELATIONSHIPS IN SPHERICAL COORDINATES

Dyadic  $\bar{\bar{a}}$  can be written as

$$\bar{\bar{a}} = \mathbf{a}'_R \mathbf{u}_R + \mathbf{a}'_\theta \mathbf{u}_\theta + \mathbf{a}'_\varphi \mathbf{u}_\varphi = \mathbf{u}_R \mathbf{a}_R + \mathbf{u}_\theta \mathbf{a}_\theta + \mathbf{u}_\varphi \mathbf{a}_\varphi.$$

The basic differential operators are

$$\begin{aligned}\text{grad } \mathbf{a} &= \left( \text{grad } a_R - \frac{a_\varphi \mathbf{u}_\varphi}{R} - \frac{a_\theta \mathbf{u}_\theta}{R} \right) \mathbf{u}_R + \left( \text{grad } a_\theta + \frac{a_R \mathbf{u}_\theta}{R} - \frac{a_\varphi \mathbf{u}_\varphi}{R \tan \theta} \right) \mathbf{u}_\theta \\ &\quad + \left[ \text{grad } a_\varphi + \left( \frac{a_R}{R} + \frac{a_\theta}{R \tan \theta} \right) \mathbf{u}_\varphi \right] \mathbf{u}_\varphi \\ &= \mathbf{u}_R \frac{\partial \mathbf{a}}{\partial R} + \mathbf{u}_\theta \frac{1}{R} \frac{\partial \mathbf{a}}{\partial \theta} + \mathbf{u}_\varphi \frac{1}{R \sin \theta} \frac{\partial \mathbf{a}}{\partial \varphi}\end{aligned}\quad (\text{A4.86})$$

$$\begin{aligned}\text{div } \bar{\bar{a}} &= \left( \text{div } \mathbf{a}'_R - \frac{a_{\theta\theta} + a_{\varphi\varphi}}{R} \right) \mathbf{u}_R + \left( \text{div } \mathbf{a}'_\theta + \frac{a_{\theta R}}{R} - \frac{a_{\varphi\varphi}}{R \tan \theta} \right) \mathbf{u}_\theta \\ &\quad + \left( \text{div } \mathbf{a}'_\varphi + \frac{a_{\varphi R}}{R} + \frac{a_{\varphi\theta}}{R \tan \theta} \right) \mathbf{u}_\varphi \\ &= \frac{\partial \mathbf{a}_R}{\partial R} + \frac{2\mathbf{a}_R}{R} + \frac{1}{R} \frac{\partial \mathbf{a}_\theta}{\partial \theta} + \frac{\mathbf{a}_\theta}{R \tan \theta} + \frac{1}{R \sin \theta} \frac{\partial \mathbf{a}_\varphi}{\partial \varphi}\end{aligned}\quad (\text{A4.87})$$

$$\begin{aligned}
 \text{curl } \bar{\bar{a}} &= \left( \text{curl } \mathbf{a}'_R + \frac{\mathbf{a}'_\theta \times \mathbf{u}_\theta}{R} + \frac{\mathbf{a}'_\varphi \times \mathbf{u}_\varphi}{R} \right) \mathbf{u}_R + \left( \text{curl } \mathbf{a}'_\theta - \frac{\mathbf{a}'_R \times \mathbf{u}_\theta}{R} + \frac{\mathbf{a}'_\varphi \times \mathbf{u}_\theta}{R \tan \theta} \right) \mathbf{u}_\theta \\
 &\quad + \left( \text{curl } \mathbf{a}'_\varphi - \frac{\mathbf{a}'_R \times \mathbf{u}_\varphi}{R} - \frac{\mathbf{a}'_\theta \times \mathbf{u}_\varphi}{R \tan \theta} \right) \mathbf{u}_\varphi \\
 &= \mathbf{u}_R \left( \frac{1}{R} \frac{\partial \mathbf{a}_\varphi}{\partial \theta} + \frac{\mathbf{a}_\varphi}{R \tan \theta} - \frac{1}{R \sin \theta} \frac{\partial \mathbf{a}_\theta}{\partial \varphi} \right) \\
 &\quad + \mathbf{u}_\theta \left( \frac{1}{R \sin \theta} \frac{\partial \mathbf{a}_R}{\partial \varphi} - \frac{\partial \mathbf{a}_\varphi}{\partial R} - \frac{\mathbf{a}_\varphi}{R} \right) + \mathbf{u}_\varphi \left( \frac{\partial \mathbf{a}_\theta}{\partial R} + \frac{\mathbf{a}_\theta}{R} - \frac{1}{R} \frac{\partial \mathbf{a}_R}{\partial \theta} \right). \quad (\text{A4.88})
 \end{aligned}$$

In particular:

$$\text{grad } \mathbf{u}_R = \frac{\mathbf{u}_\theta \mathbf{u}_\theta}{R} + \frac{\mathbf{u}_\varphi \mathbf{u}_\varphi}{R} \quad (\text{A4.89})$$

$$\text{grad } \mathbf{u}_\theta = -\frac{\mathbf{u}_\theta \mathbf{u}_R}{R} + \frac{\mathbf{u}_\varphi \mathbf{u}_\varphi}{R \tan \theta} \quad (\text{A4.90})$$

$$\text{grad } \mathbf{u}_\varphi = -\frac{\mathbf{u}_\varphi \mathbf{u}_R}{R} - \frac{\mathbf{u}_\theta \mathbf{u}_\theta}{R \tan \theta} \quad (\text{A4.91})$$

$$\text{grad}(\mathbf{R}\mathbf{u}_R) = \bar{\bar{I}}. \quad (\text{A4.92})$$

## NOTES

In addition to [12, 165, 173] of the general bibliography:

I. V. Lindell, *Elements of Dyadic Algebra and Its Application in Electromagnetics*. Report S126, Radio Laboratory, Helsinki University of Technology, 1981.

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C. T. Tai, Some essential formulas in dyadic analysis and their applications. *Radio Sci.* **22**, 1283–1288, 1987.